

**Phys 410**

**Fall 2015**

**Homework #7**

**Due Thursday, 29 October, 2015**

All problems are from Taylor, *Classical Mechanics*.

- 1) Problem 7.31 Pendulum with oscillating point of suspension
- 2) Problem 7.34 Harmonic oscillation with spring of non-zero mass
- 3) Problem 7.35 Rotating loop with bead
- 4) Problem 7.37 Rotating mass on table
- 5) Problem 7.41 Bead on a rotating parabola
- 6) Problem 8.1 Two-particle problem
- 7) Problem 8.3 Two particles interacting by means of a spring
- 8) Problem 8.6 Angular momentum
- 9) Problem 8.9 Two-dimensional harmonic motion
- 10) Problem 8.12 Planetary angular momentum
- 11) Is the motion a minimum in the action or a saddle point? Consider the case of a simple harmonic oscillator.
  - a) Write down the Lagrangian for a one-dimensional simple harmonic oscillator (mass on a spring, no gravity, no friction) in terms of the coordinate  $x$ , its time derivative  $\dot{x}$ ,  $m$  and  $k$ , where  $m$  is the mass and  $k$  is the spring constant. Let  $x_0(t)$  be the true path of the oscillator, so that  $x_0(t)$  satisfies the SHO equation of motion. We now consider variations on this path of the form  $x_0(t) + \xi(t)$ , where  $\xi(t)$  goes to zero at  $t = 0$  and  $t = t_1$ . If  $S[\xi]$  represents that action for the variation  $\xi$ , show that

$$S[\xi] = \int_0^{t_1} \left( \frac{m}{2} (\dot{x}_0^2 + \dot{\xi}^2) - \frac{k}{2} (x_0^2 + \xi^2) \right) dt$$

Hint: you will have cross terms involving  $x_0$ ,  $\xi$ , and their first derivatives. Use integration by parts and the fact that  $x_0$  satisfies the equation of motion to eliminate these terms.

- b) Let's assume that the true path  $x_0(t)$  represents a stationary point in the action. (In fact it is a stationary point, as required by Hamilton's Principle.) What we would like to understand is whether  $x_0(t)$  is a minimum in the action or a saddle point in the action. To address this question, we will consider whether the variation  $\xi(t)$  increases or decreases the action in the neighborhood of  $x_0(t)$ . As always, we will only consider fixed time intervals, in this case the time interval from  $t = 0$  to  $t = t_1$ . Let  $S_0 =$

$S[\xi = 0]$ , the action for the true path, and let  $\Delta S = S[\xi] - S_0$ , so that  $\Delta S$  is the change in the action due to variation  $\xi(t)$ . Then we have

$$\Delta S = S[\xi] - S_0 = \frac{1}{2} \int_0^{t_1} (m\dot{\xi}^2 - k\xi^2) dt$$

Let's choose a simple triangle function for the variation:

$$\xi(t) = \begin{cases} \frac{\varepsilon t}{t_1}, & 0 \leq t \leq \frac{t_1}{2} \\ \varepsilon \left(1 - \frac{t}{t_1}\right), & \frac{t_1}{2} \leq t \leq t_1 \end{cases}$$

Find the condition for  $t_1$  under which  $\Delta S$  is negative (where the variation has decreased the action), and compare this value of  $t_1$  to the full period of the oscillator. *Remark:* We know that we always *increase* the action around the true path by increasing the kinetic energy term with a high-frequency, small amplitude wiggle. Since the example of the triangle function shows that it is also possible to find variations that *decrease* the action (at least in some situations), this shows that the true path  $x_0(t)$  represents a *saddle point* in the action for those cases, not a minimum. In other words, the action may increase or decrease around the true path, depending on the exact nature of the variation that is considered, and depending on the choice of  $t_1$ . This is why we should refer to Hamilton's Principle as 'the principle of stationary action' and not 'the principle of least action.'

c) Repeat part b) for a variation of the type  $\xi(t) = \varepsilon \sin(\pi t/t_1)$ .

Extra Credit

1) Problem 8.14 Orbits with different central force laws